

# ***Quantitative assessment of C-band and X-band SRTM datasets over the CEOS-WGCV-TMSG test sites and intercomparison of C-band DEM with the OS® PANORAMA DTM***

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HRSC Science Team Member (ESA Mars Express 2003)*

# Overview

- **Context: CEOS-WGCV “Terrain Mapping from satellites” Sub-Group (TMSG)**
- **TMSG test sites - description and location**
- **Evaluation of SRTM C and X DEMs for UK test site**
- **Interpretation of SRTM elevation differences:**
  - **Forest mapping**
  - **Slope/Aspect effects**
  - **Mining activities**
- **Inter-comparison of SRTM DEM products with NextMap**
- **Use of SRTM for improving ERS-tandem DEMs**
- **Evaluation of SRTM accuracy and completeness for Spanish test sites**
- **Conclusions**



# CEOS WGCV Terrain Mapping

- **What is CEOS WGCV**
  - Committee on Earth Observing Satellites
  - Working Group on Calibration/Validation (Chair: S. Ungar, GSFC)
- **What is the mission of this sub-group?**
  - To ensure that characteristics of digital terrain models produced from Earth Observation sensors at global and regional scale are well understood and that products are validated and used for appropriate applications.
- **What are the specific objectives of this group?**
  - To develop specifications for the generation of ‘*standardised terrain surface products with known accuracy*’ from similar sensing systems in the context of data continuity,
  - to specify evaluation methods and statistics which give transparent information about the *quality and heritage of terrain models*.
  - To produce and update the current dossier of test sites and identify new sites, particularly to satisfy the cal/val requirements of future missions and generally improve access to validation data sets.
- **Why are space agencies interested in topography?**
  - To ensure that geometric and radiometric errors in land products derived from satellites are corrected with the best available data
  - Science requirements covering all the application areas of interest
  - GEOSS social action agenda

# ***Objectives of validation study***

- **Quality assessment of C- and X-SRTM DEMs using “bare earth” DTMs, high-resolution airborne DSMs and kinematic GPS**
- **Assess whether they meet the design specification for DTED-1 ( $Z_{rms} \leq 18m$ ) and DTED-2 ( $Z_{rms} \leq 12m$ )**
- **Assess planimetric height accuracy via intercomparisons with “bare earth” DTMs**
- **Interpret height differences in terms of topographic variables, LANDSAT-derived enhanced vegetation index (EVI) and land cover**



# Test site Data Sets

## Global CEOS WGCV-TMSG test sites

- **Locations:**
  - Snowdonia, UK
  - Catalonia, Spain
  - Aix en Provence, France
  - Bavaria, Germany
  - Puget Sound, WA, USA (data available online from CEOS-WTF at EDC)
- **Criteria for selection based on availability of ground truth and previous use for validation of spaceborne DEMs**
- **Input data sets - most at 1 arc-second ( $\approx 30\text{m}$ ):**
  - LANDMAP ERS-tandem (UK only)
  - C-Band (3") both JPL unedited and NGA edited (SRTM-DTED®, courtesy of Jim Slater, NGA and EDC prior to public release)
  - X-Band (1" converted to geoid) SRTM DSMs (Snowdonia, Catalonia)
  - Reference Data (DTMs, LANDSAT-7, 5)
  - Stereo optical DEM from Spot1 of Aix en Provence
  - Stereo optical DEMs from SPOT-5 HRS of all 3 non-UK sites
  - NextMap 5m DSM of Snowdonia, UK sub-areas (courtesy of B. Mercer, Intermap)
  - NASA-sponsored lidar DSM and DTM (2m) of Puget Sound

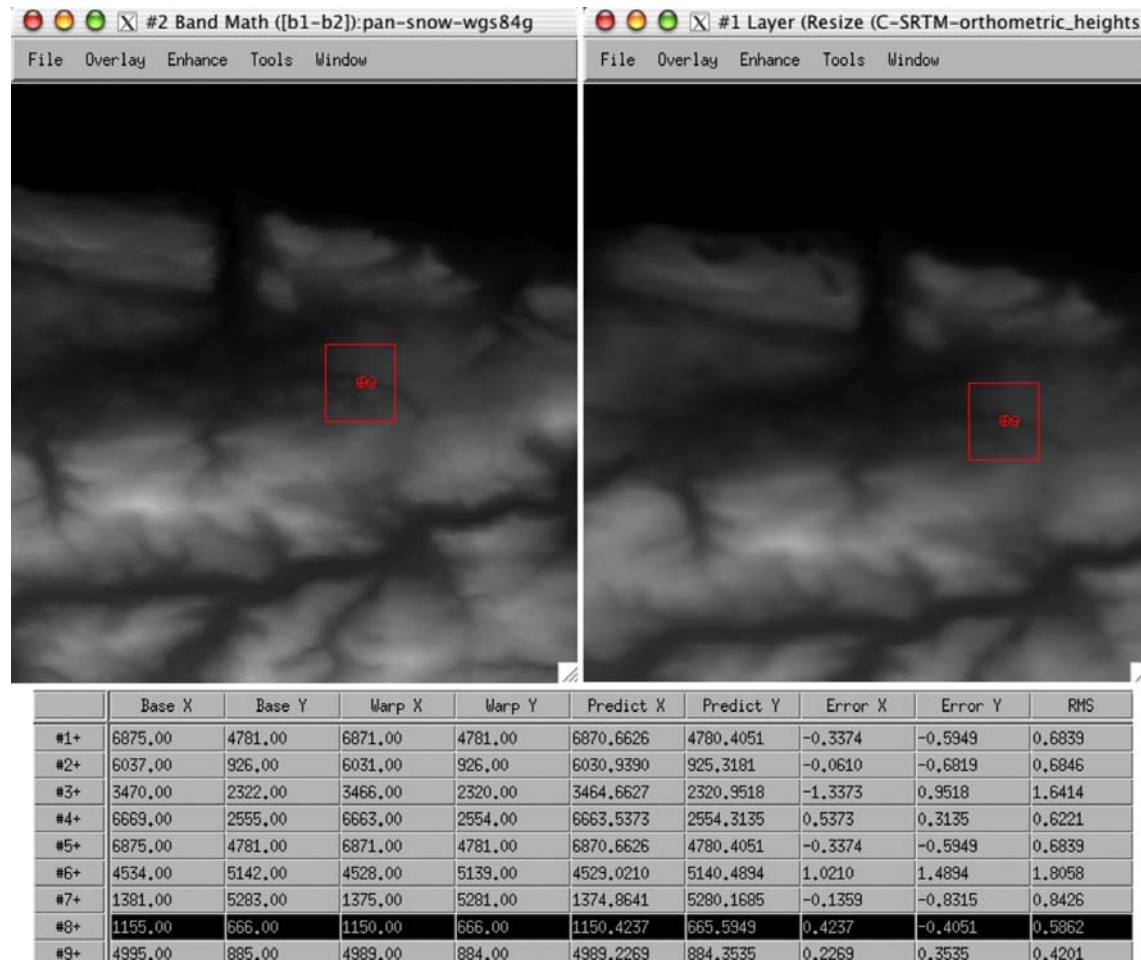


# Critical Pre-processing Steps

Global CEOS WGCV-TMSG test sites

- Initial evaluation using side-side display, Red/Green displays and flickering in ENVI/IDL®, ARCGIS® and ERDAS-IMAGINE® showed that there were planimetric shifts between SRTM and “ground truth” DEMs of between 1 to 2 (and occasionally up to 4) DEM grid-cell points (either resampled 50m OS® or 3”)
- C-SRTM showed an overall translation wrt “ground truth” DTMs (either derived from generalised contours, e.g. OS® PANORAMA® or photogrammetrically derived DEMs)
- X-SRTM showed spatially variable higher order effects
- Datums checked, kGPS checked and no apparent differences between the different software packages
- Shifts also present between Star-3i (NextMap) and C-SRTM whereas there was NO shift with ground truth DTMs or ERS-tandem DEMs or SPOT-stereo DEMs
- Initial height difference maps showed that the differences were dominated by these planimetric shifts
- After selection of well-distributed GCPs a 1st order polynomial used to warp the two DEMs which removed almost all visible differences
- Horizontal shifts also present between JPL unedited SRTM and edited SRTM-DTED® probably due to the effects of thinning vs averaging

# Example of planimetric shifts at GCPs



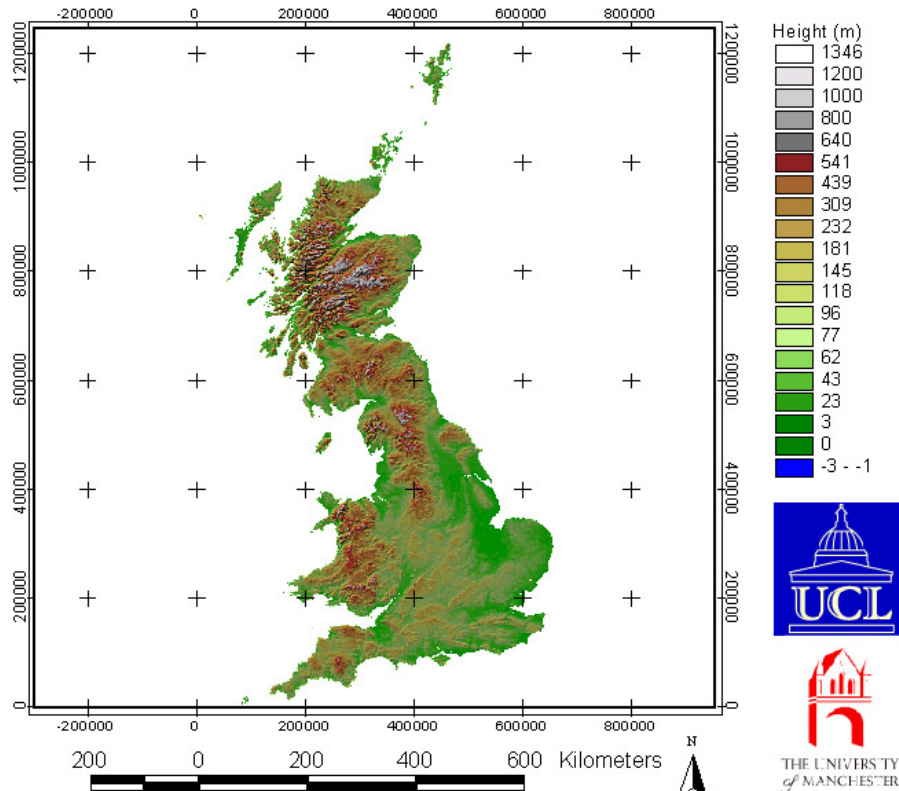
N.B. Initial assessments made using river confluences because of the difficulty in manual measurements.



# Intercomparison of OS® PANORAMA® (50m) and LANDMAP IfSAR DEM (30m)

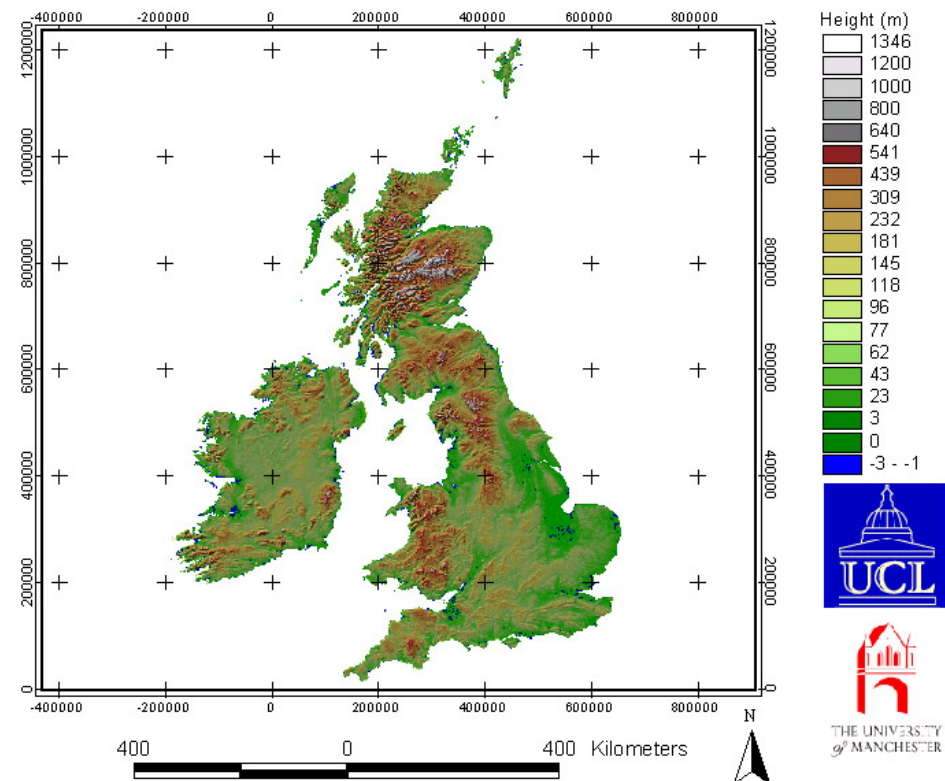
## Coloured and Hillshaded Panorama DEM - UK

50m DEM aggregated to 1km on Ordnance Survey National Grid



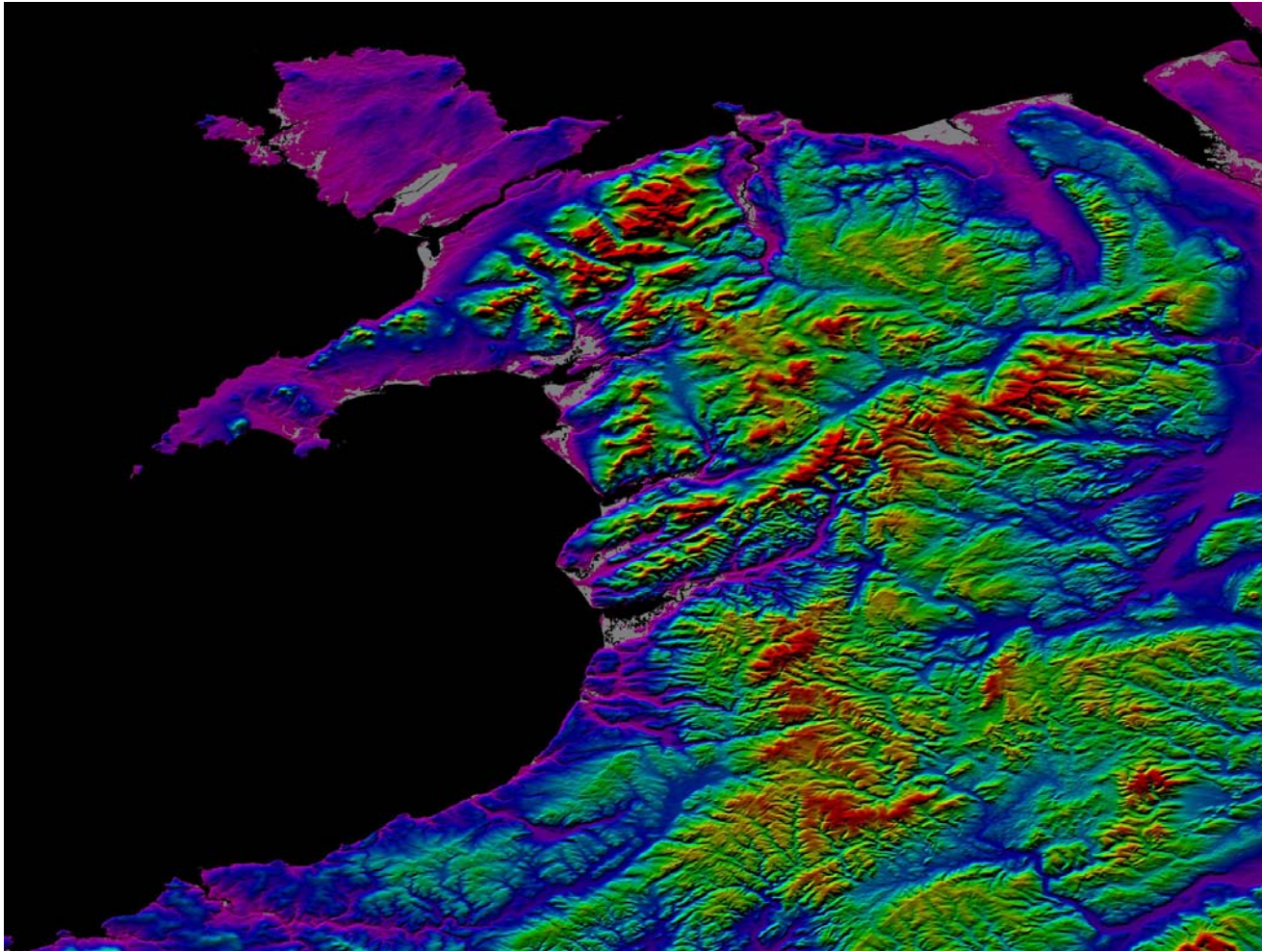
## Coloured and Hillshaded LANDMAP DEM - British Isles

1" DEM Projected to Ordnance Survey National Grid at 1km pixel spacing





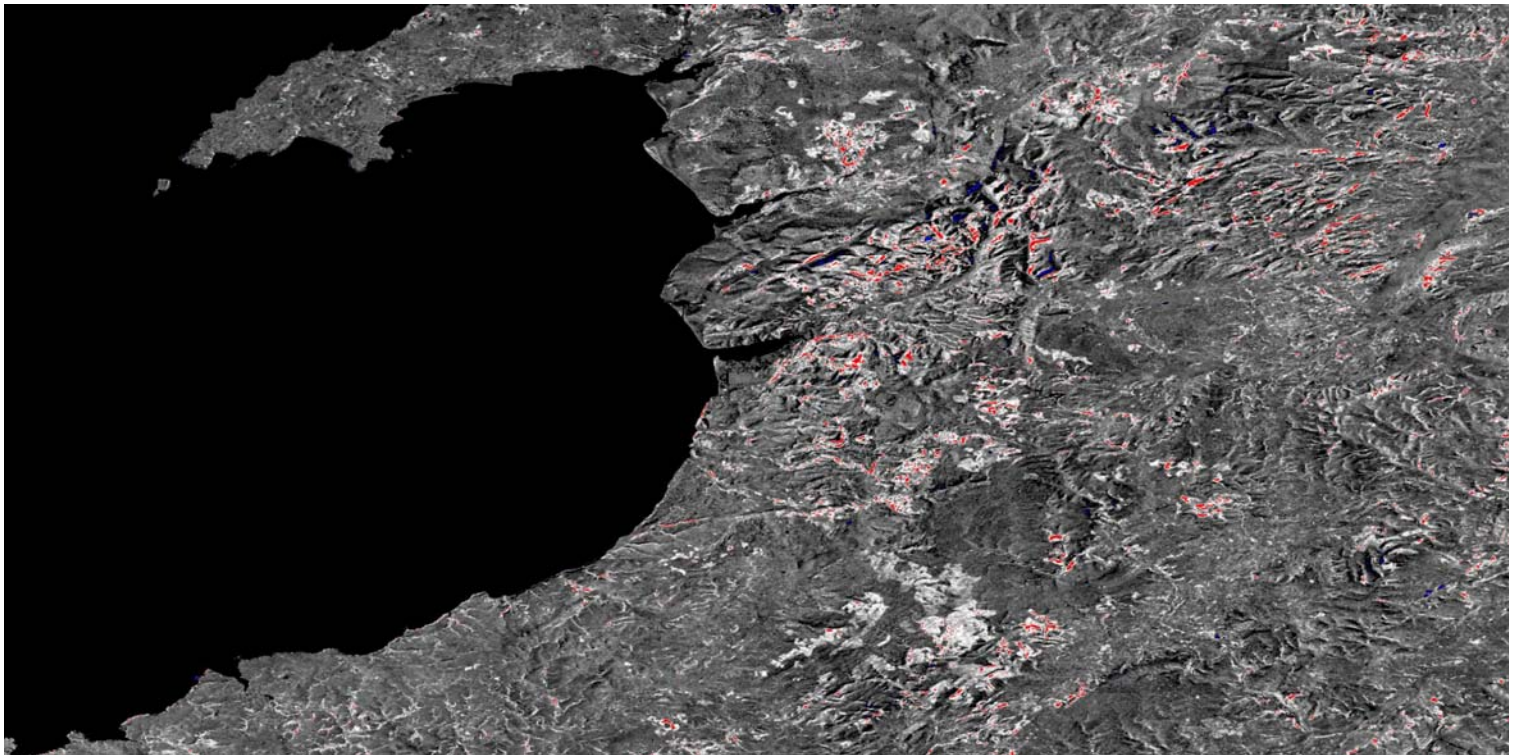
# ***Snowdonia North Wales, UK - CSRTM DEM***



# CSRTM-OS®

**Red ( $>17m$ ), Blue ( $<-17m$ )**

***AFTER co-registration using tiepoints and “warping”***



Height differences  
Dominated by:  
Radar shadows &  
Forest cover.

1.22±4.13m overall  
but for DEM  
differences  
excluding forest  
and radar shadow  
Is  $\approx 1-2m$ !!





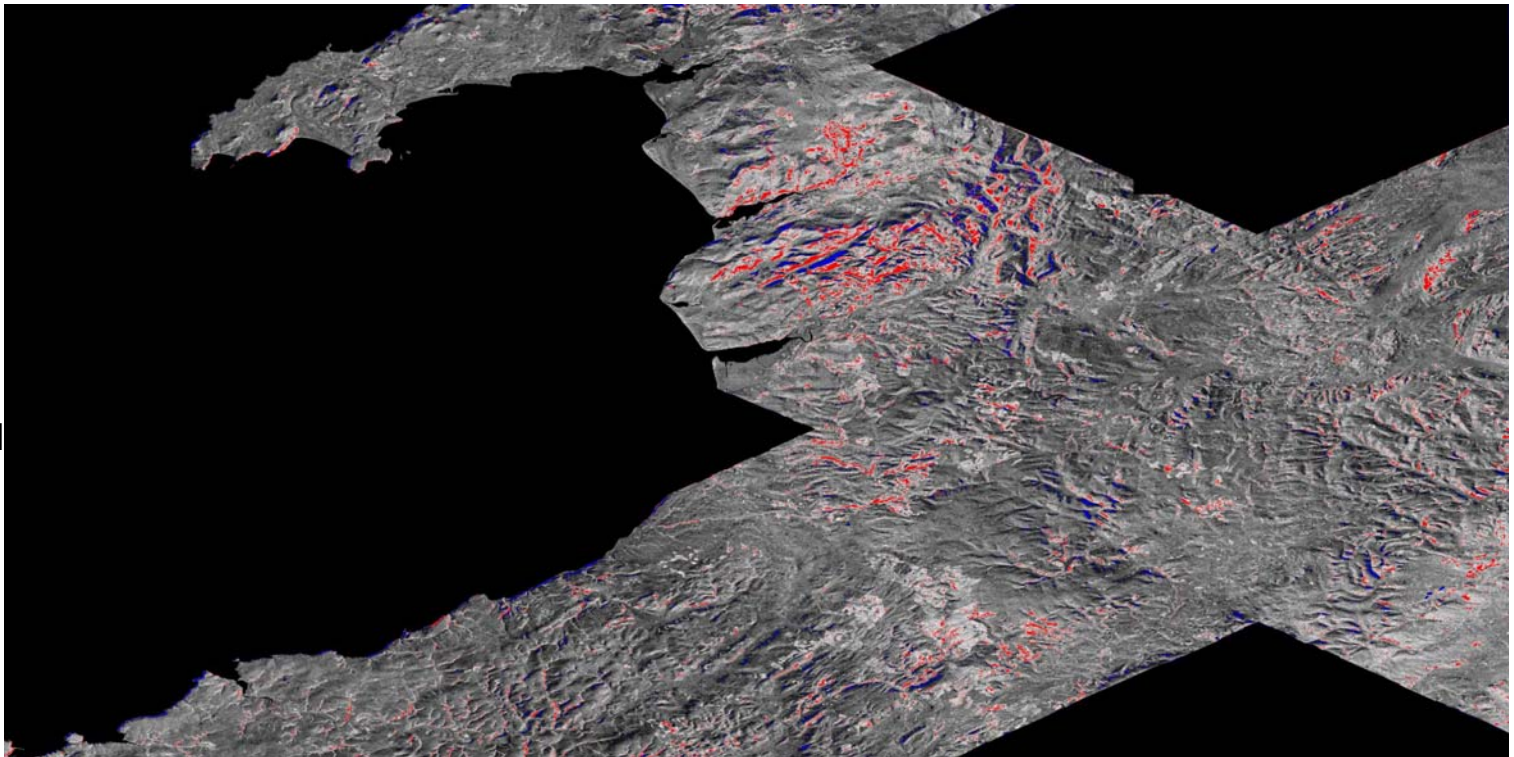
# ***XSRTM-OS®***

***Red (>17m), Blue (<-17m)***

***AFTER co-registration using tiepoints and “warping”***

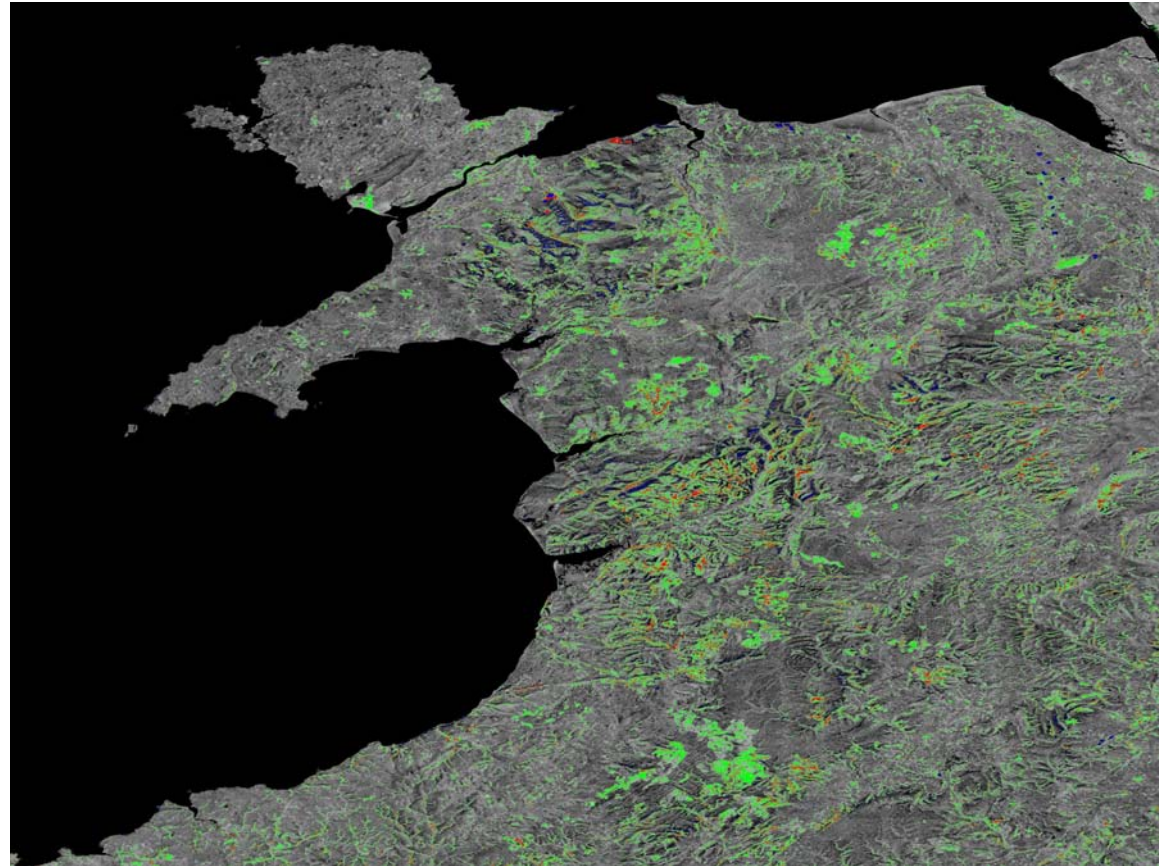
Height differences  
Dominated by:  
Radar shadows &  
Forest cover.

0.26±6.12m overall  
Planimetric offsets  
spatially variant.



# ***CSRTM-OS®***

## ***Green ( $\partial Z=9-16m$ )***

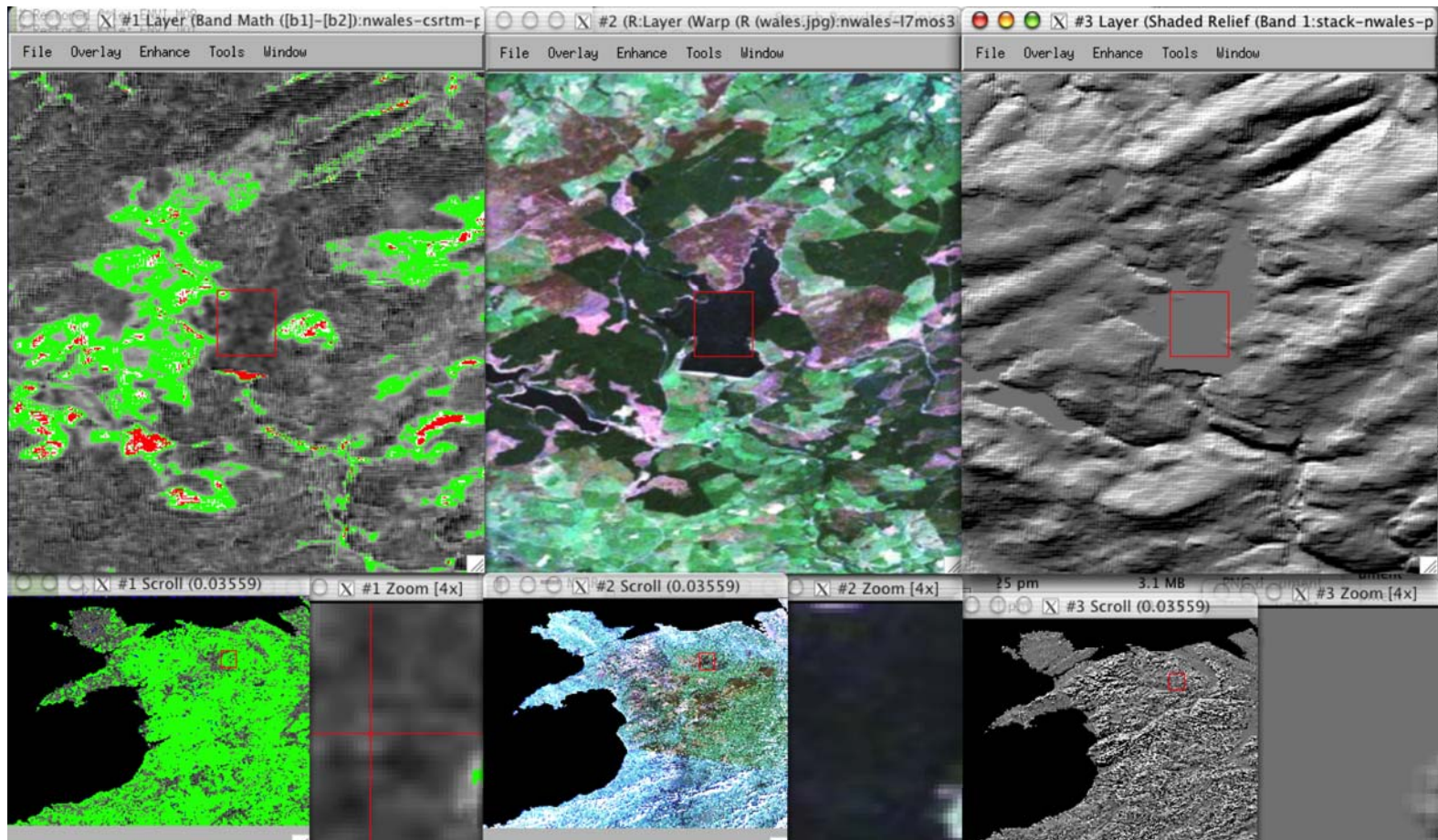


Height differences  
in this range are  
closely linked to forest cover  
In this region





# Example area showing impact of forest cover ( $\text{Green} = \Delta Z = 9-16\text{m}$ )



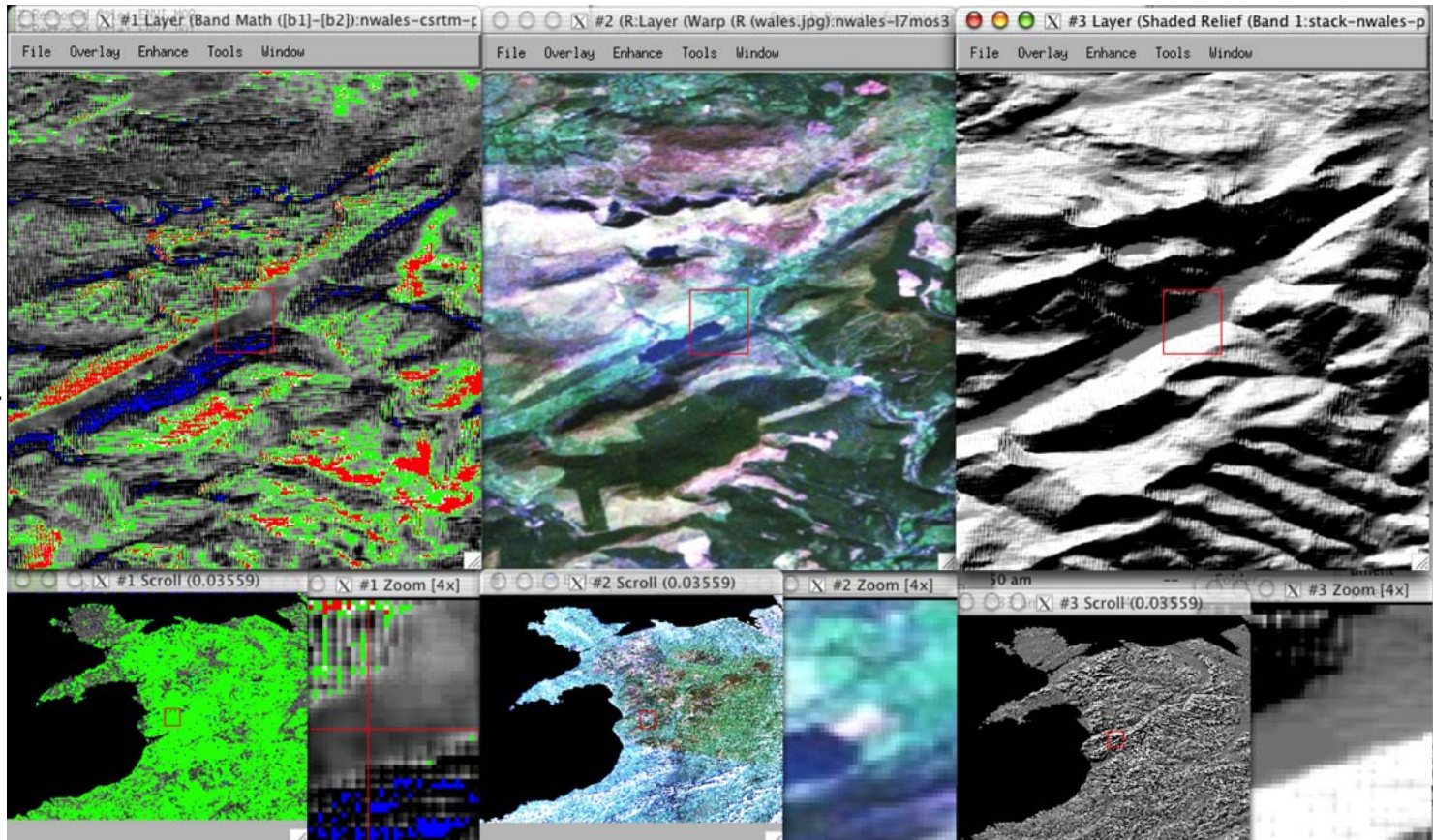
CSRTM-OS®

Landsat 7 (3,2,1)

OS® PANORAMA®



# *Example area showing impact of slope/aspect + forest cover*



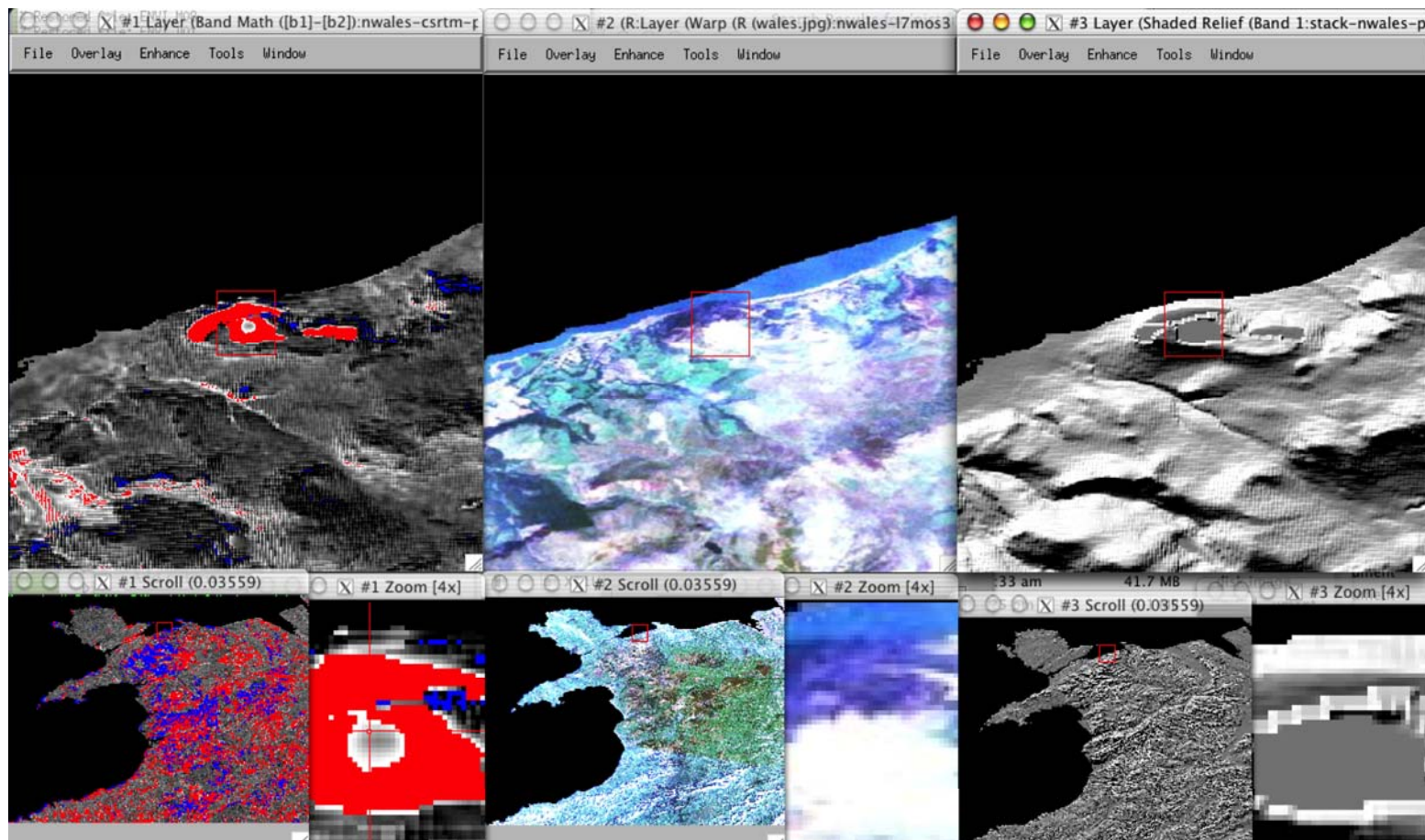
N.B. Limited examples of Slope/aspect effects. Cannot unscramble these due to impact of mosaicing of multiple "looks"

CSRTM-OS®

Landsat 7 (3,2,1)

OS® PANORAMA®

# Example of landscape change from CSRTM-OS®: Mining Activities



CSRTM-OS®

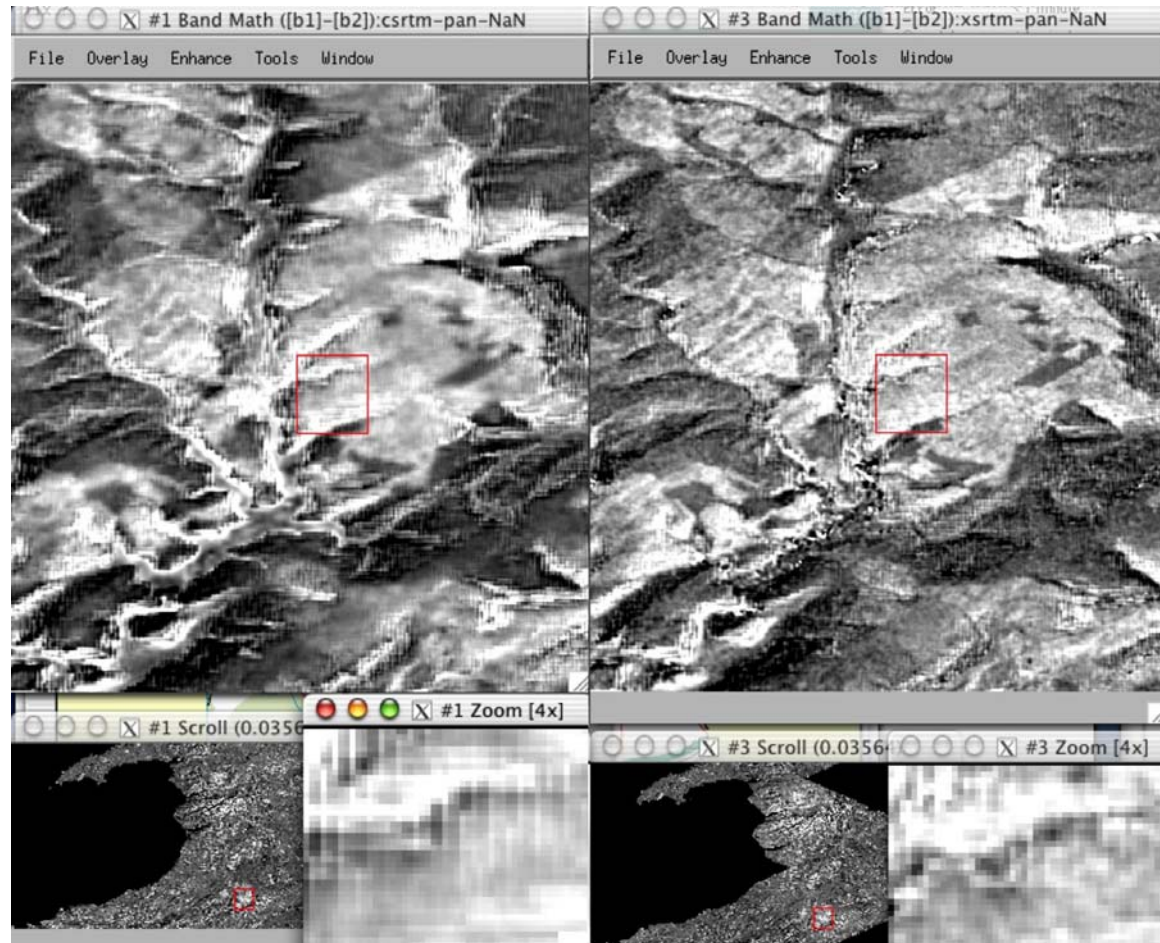
Landsat 7 (3,2,1)

OS® PANORAMA®

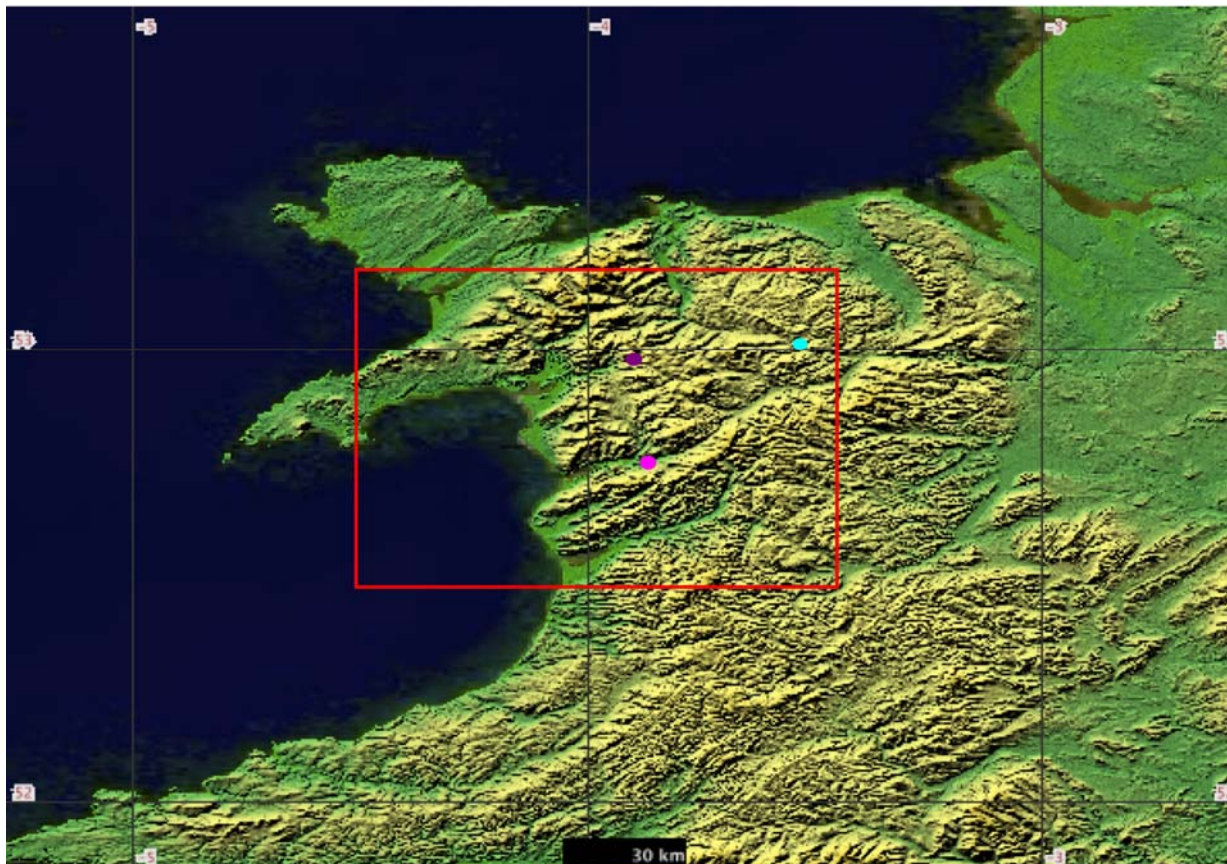


# Intercomparison of CSRTM-OS® and XSRTM-OS®

N.B. 1" XSRTM and 3" CSRTM differences with OS® DTM show little substantive differences. Little radar penetration at CSRTM for this area.



# North Wales test-sites for NextMap® DSMs

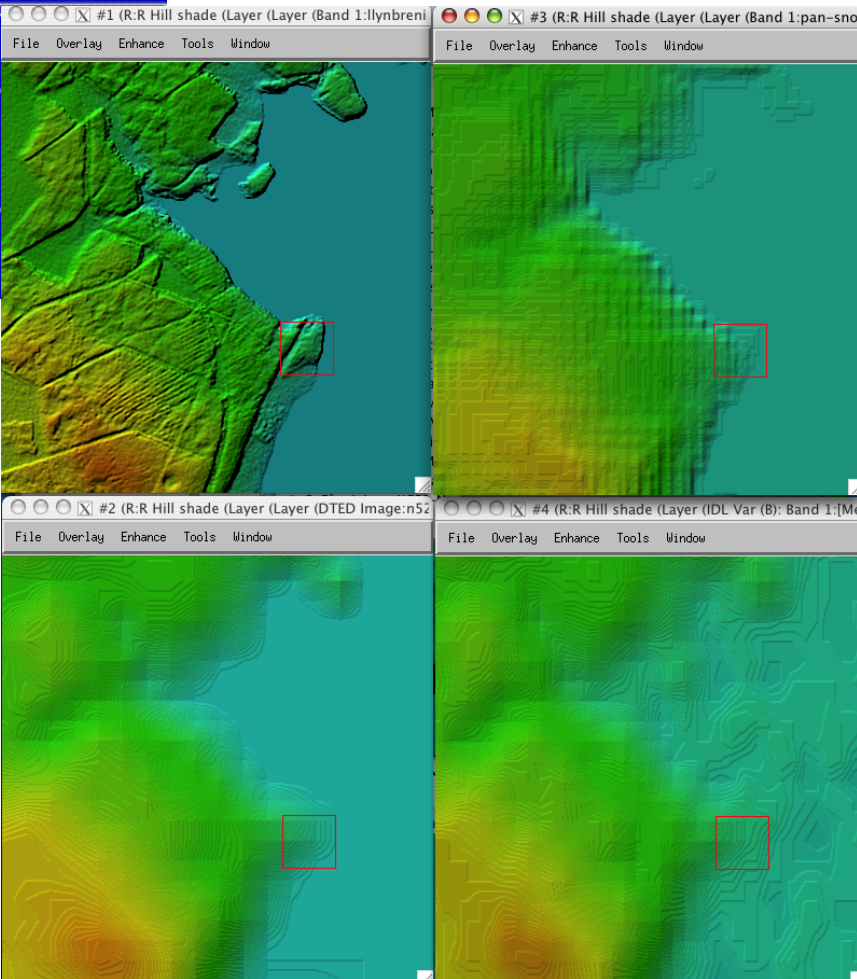


N.B. Three coloured dots refer to three 10 x 10km NextMap test areas (courtesy of B. Mercer, InterMap technologies). NO co-registration performed





# Summary of inter-comparison stats



Minffordd	Min	Max	Mean	Stdev
NextMap-PAN	-94.22	85.33	5.73	16.29
JPL-PANORAMA	-701.00	154.00	2.27	35.88
DTED-PANORAMA	-717.00	134.00	2.28	29.84
JPL-DTED	-482.00	698.00	0.07	10.37
JPL-NextMap	-712.16	125.61	-3.45	28.20
DTED-NextMap	-738.42	102.61	-3.44	23.31

LlynBrenig	Min	Max	Mean	Stdev
NextMap-PAN	-54.75	47.07	-4.43	7.37
JPL-PANORAMA	-160.00	63.00	3.07	11.32
DTED-PANORAMA	-50.00	57.00	3.13	9.48
JPL-DTED	-161.00	17.00	-0.06	2.46
JPL-NextMap	-176.79	50.82	-1.36	9.01
DTED-NextMap	-50.45	43.39	-1.30	7.37

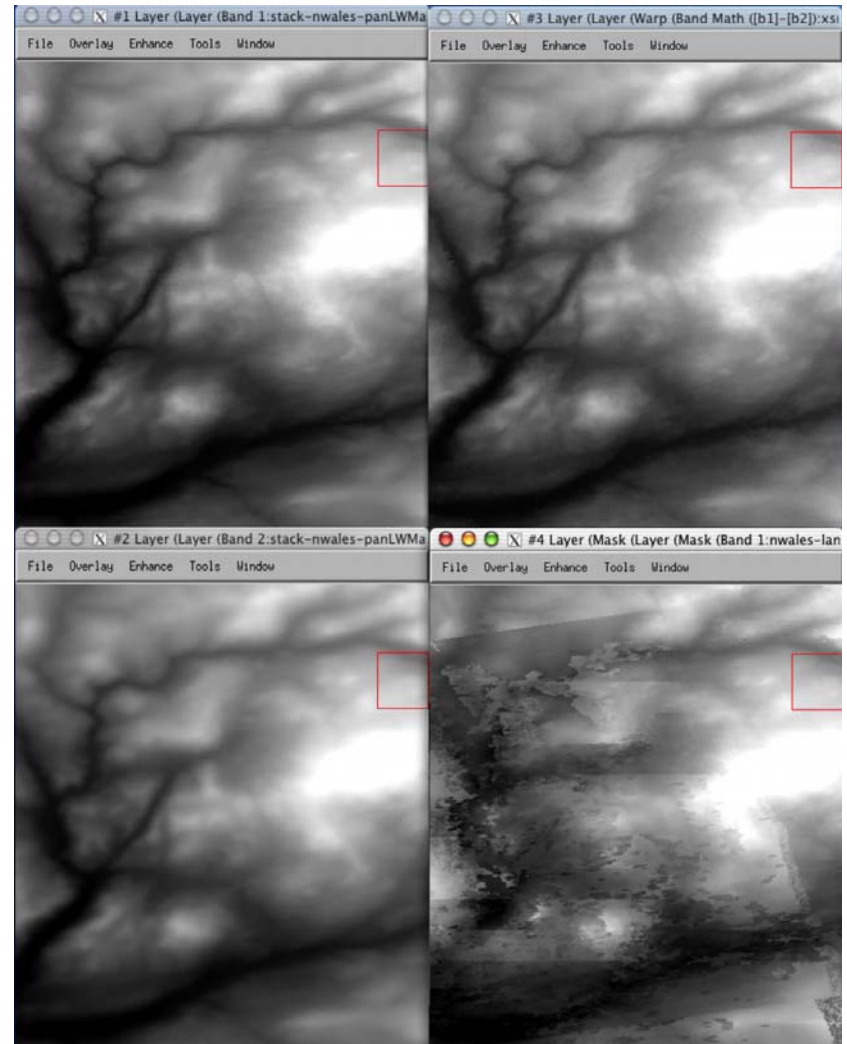
Ffestiniog	Min	Max	Mean	Stdev
NextMap-PAN	-74.46	46.47	-3.50	7.50
JPL-PANORAMA	-93.00	100.00	5.31	14.48
DTED-PANORAMA	-80.00	82.00	4.45	12.19
JPL-DTED	-19.00	23.00	0.86	2.76
JPL-NextMap	-72.90	74.66	1.82	10.46
DTED-NextMap	-62.36	63.66	0.95	8.52

NextMap (UL), OS PANORAMA (UR), SRTM-DTED1 (LR), JPL-SRTM (LR)

LlynBrenig

# *Inter-comparison of SRTM and LANDMAP*

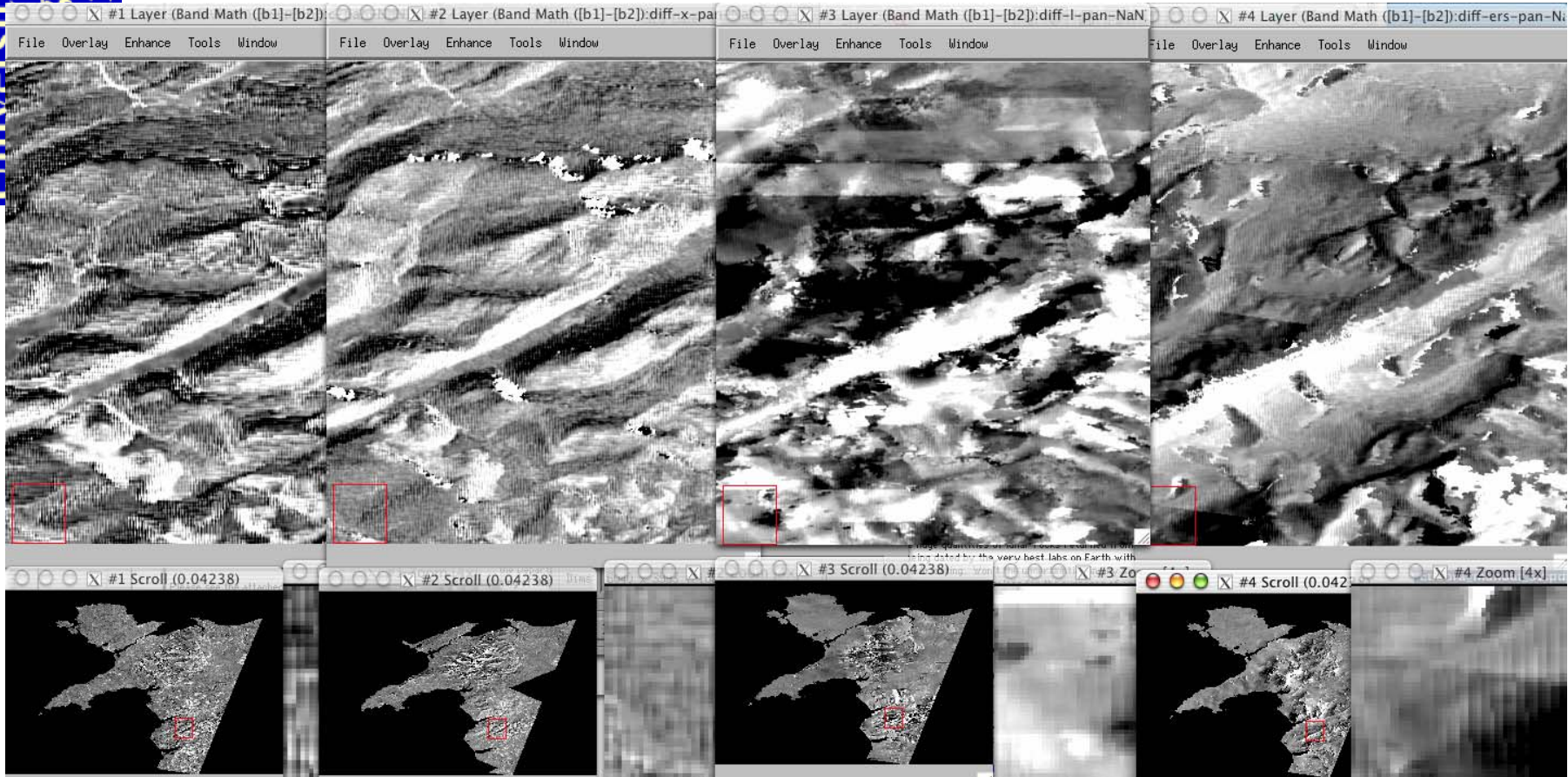
- Little difference between OS® (UL), X-SRTM (UR) C-SRTM (LL)
- ERS-tandem LANDMAP (LR) shows strong atmospheric artifacts and blocking due to phase unwrapping methods (MCF)
- SRTM DEMs were then employed for phase reference for ERS-tandem for subsequent processing.





# Use of C-SRTM for densifying ERS-tandem to 30m

## Some impact on minimising atmospheric and blocking artifacts.



CSRTM-OS®  
0.59±3.16m

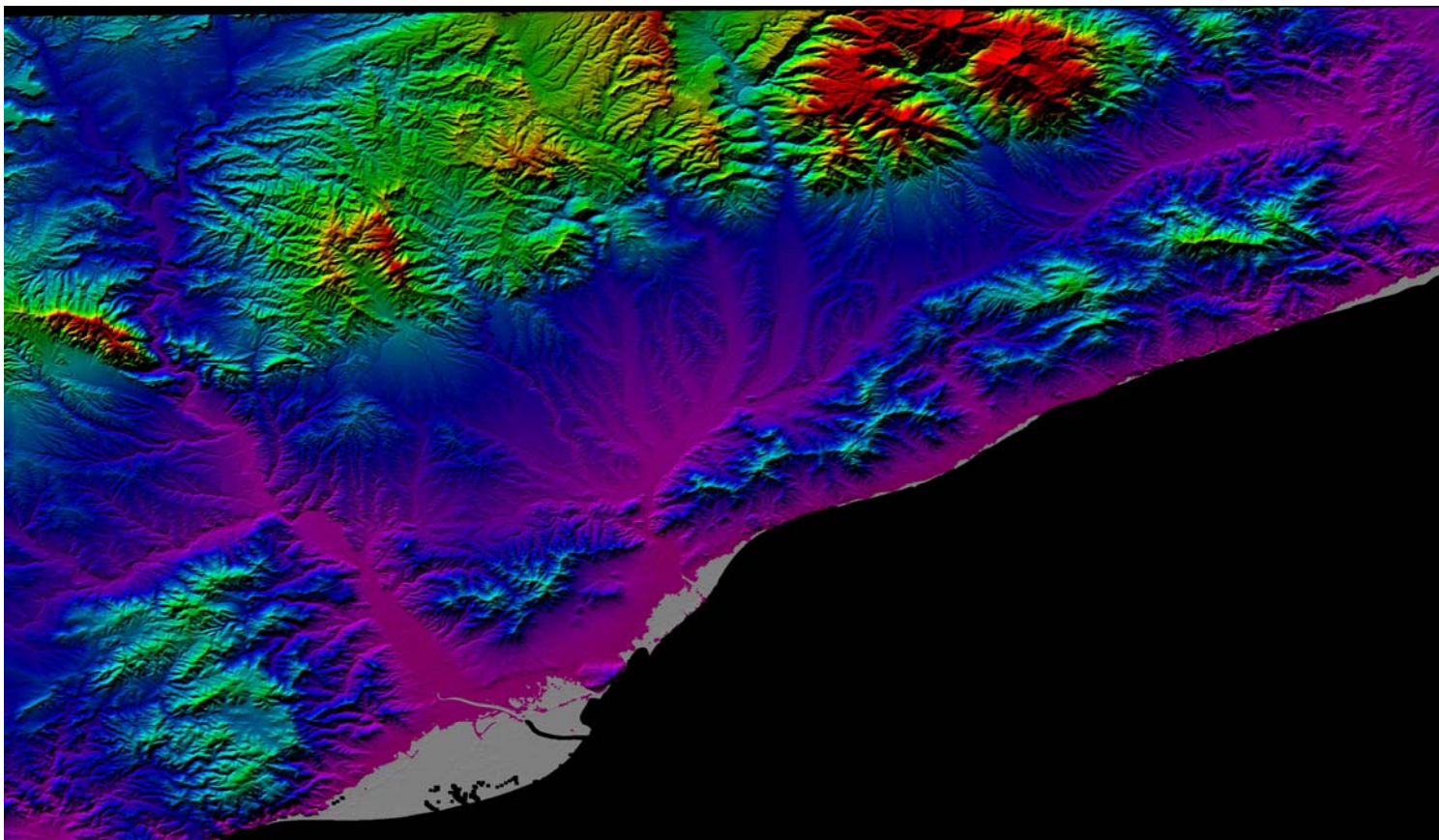
XSRTM-OS®  
0.04±5.74m

LANDMAP-OS®  
-0.1±17.92m

ERS(SRTM)-OS®  
-0.11±11.36m

# ***Ground Truth 2***

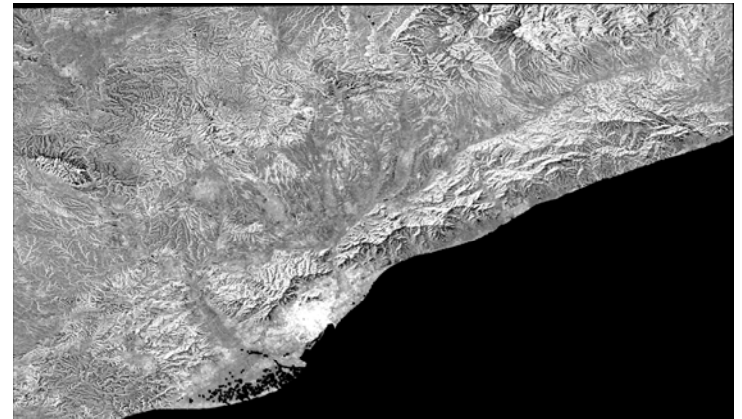
***Test Site Catalonia/Barcelona***  
***15m photogrammetric DTM ( $\pm 1.1\text{m}$ )***  
***Courtesy of W. Kornus, ICC, Barcelona***





# *Intercomparison of C- and X-SRTM DEMs with reference DTMs*

- CSRTM-reference(Upper Right) =  $3.44 \pm 5.78\text{m}$
- XSRTM-reference (Lower Right) =  $4.32 \pm 6.63\text{m}$
- Note correlation of forest with **POSITIVE** height differences



Courtesy of Dietmar Backes

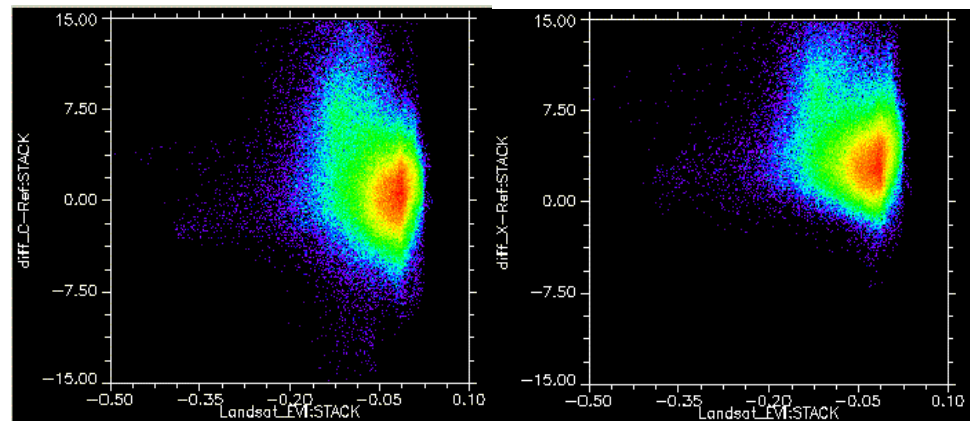
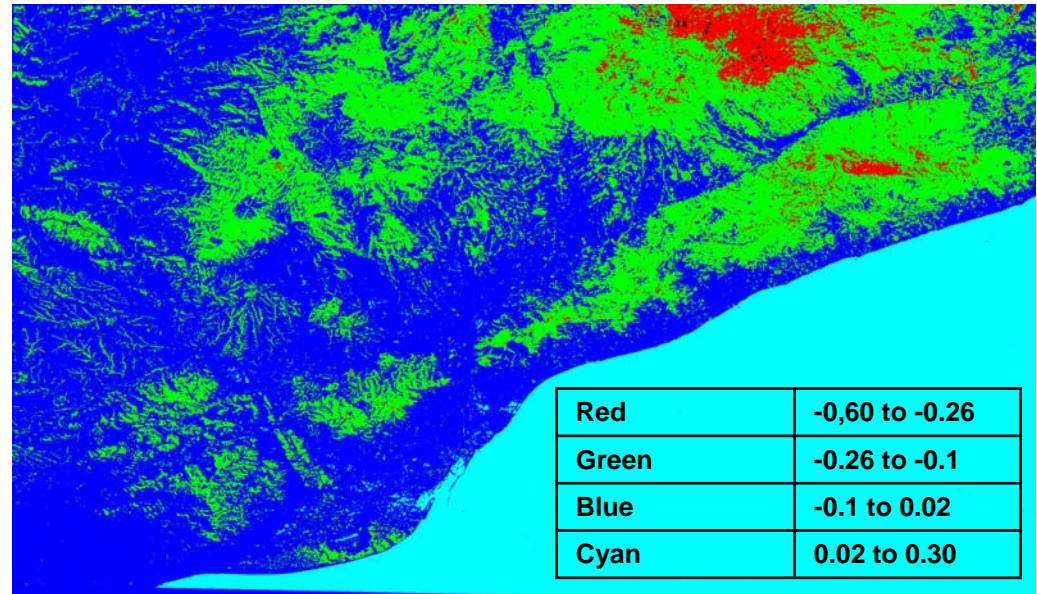




# Assessment of the relationship of height difference to EVI

$$EVI = \frac{r_{NIR} - r_{Red}}{r_{NIR} + C_1 r_{Red} - C_2 r_{Blue} + L} \times G$$

- For MODIS, MERIS and LANDSAT use
- $L=1$ ,  $C_1 = 6$ ,  $C_2 = 7.5$ , and  $G$  (gain factor) = 2.5
- Cluster of EVI in range -0.26 to -0.1



C-ref vs EVI

X-ref vs EVI

# Conclusions

- **C-SRTM and X-SRTM elevation differences for Snowdonia test site:**

1.22±4.23m (CSRTM - OS®) cf. 0.26±6.12m (XSRTM-OS®)

-0.1±17.92m (LANDMAP-OS®) cf. -0.11±11.36m (LANDMAP-OS®/C-SRTM)

- **C-SRTM and X-SRTM elevation differences for Barcelona test site.**

3.44±5.78m (CSRTM - reference)

4.32±6.63m (XSRTM- reference)

- **Vertical Accuracy much higher than original specification ( $Z_{rms} \leq 18m$ ) and DTED-2 ( $Z_{rms} \leq 12m$ ).**
- **Height differences for SRTM correlated to**
  - forest cover and EVI
  - Slope/aspect wrt radar look direction
- **Horizontal accuracy appears NOT to meet specifications for all 4 European test sites (90-360m)**
- **Co-registration issues remain for CSRTM with national DEMs but more severe for XSRTM possibly due to single swaths (lack of multiple imagings)**
- **Use of SRTM DEMs can reduce RMS in ERS tandem DEMs but some atmospheric and blocking artifacts remain**
- **Further research to assess how "bare earth" DTM can be extracted from SRTM DEMs and penetration depth of C-SRTM using lidar DSM/DTMs**

